

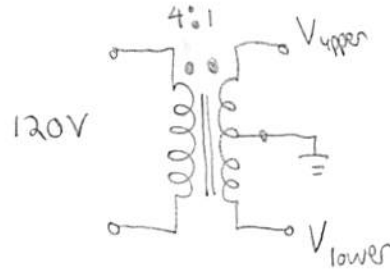
4.9

$$V_{\text{upper}} = \frac{120}{4} \times \frac{1}{2} = 15 V_{\text{rms}}$$

+9

$$V_{\text{peak}} = 15 \sqrt{2} = 21.2 V_p$$

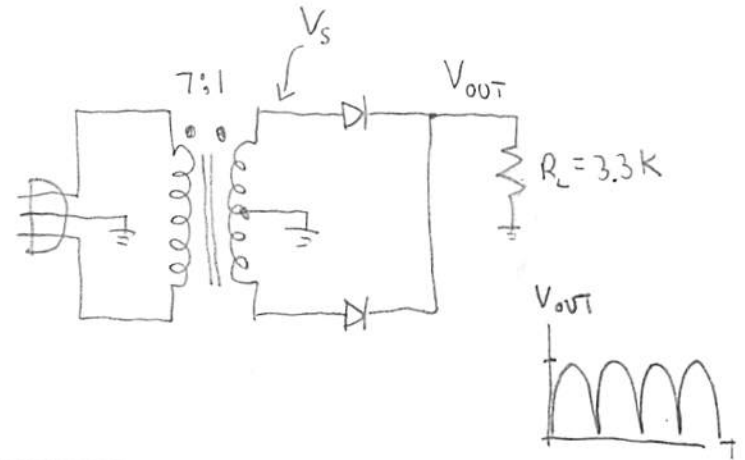
$$V_{\text{lower}} = \frac{120}{4} \times \frac{1}{2} = 15 V_{\text{rms}}$$



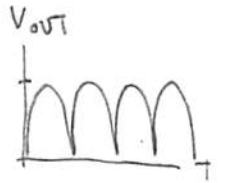
4.11

+9

$$\text{Peak } V_s = \frac{120V}{7} \times \frac{1}{2} \times \sqrt{2} = 12.1V$$

120V  
60Hz

$$\text{Peak } V_{\text{OUT}} = 12.1 - 0.7 = 11.4 V_p$$



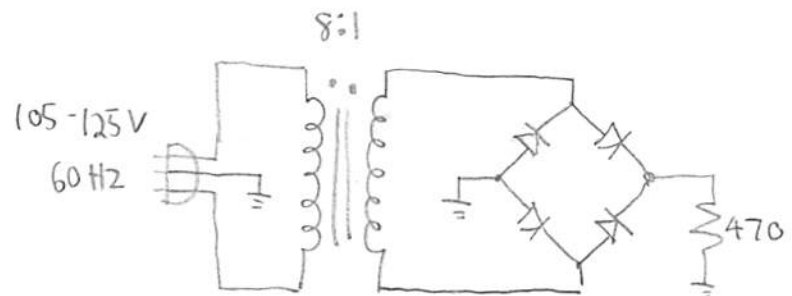
$$\text{Average value} = \text{DC value} = 2 \times \frac{11.4}{\pi} = 7.3V$$

4.14

+9

Minimum DC  
output voltage

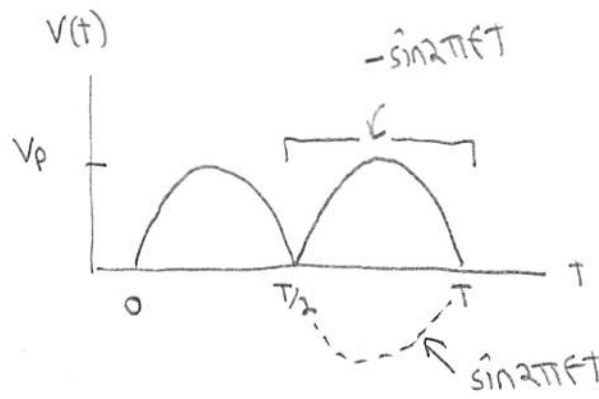
$$V_{\text{min}} = \left( \frac{105}{8} \times \sqrt{2} - 1.4 \right) \times \frac{2}{\pi} = 10.9V$$

Max DC  
output voltage

$$V_{\text{max}} = \left( \frac{125}{8} \times \sqrt{2} - 1.4 \right) \times \frac{2}{\pi} = 13.2V$$

A-xx

+5



$$\langle V \rangle = \frac{1}{T} \int_0^T v(t) dt$$

$$= \frac{1}{T} \left[ \int_0^{T/2} V_p \sin 2\pi f t dt + \int_{T/2}^T V_p (-\sin 2\pi f t) dt \right]$$

$$= \frac{V_p}{T} \left[ \frac{-1}{2\pi f} \cos 2\pi f t \Big|_0^{T/2} + \frac{1}{2\pi f} \cos 2\pi f t \Big|_{T/2}^T \right]$$

$$= \frac{V_p}{2\pi f T} \left[ -(\underbrace{\cos \pi - \cos 0}_{-2}) + (\underbrace{\cos 2\pi - \cos \pi}_{2}) \right]$$

$$= \frac{4V_p}{2\pi} = \boxed{\frac{2V_p}{\pi}} \quad \checkmark$$

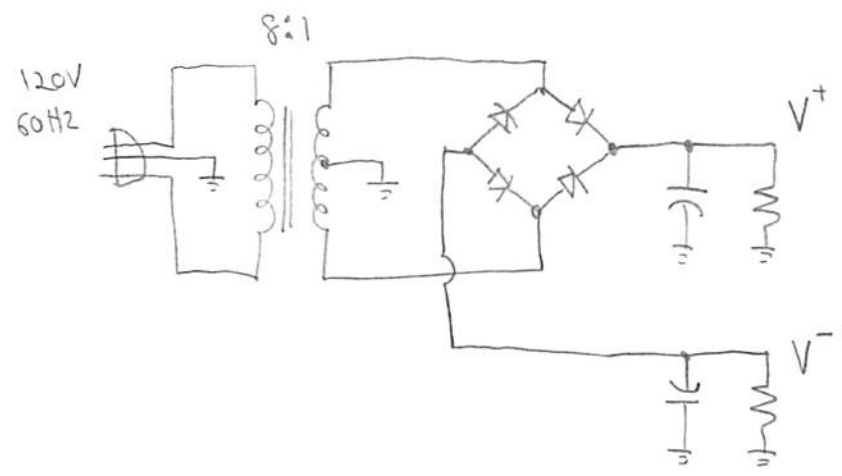
4.45 (+9)

$$V^+ = \left[ \frac{120}{8} \sqrt{2} \times \frac{1}{2} \right] - 0.7$$

$$= \boxed{9.9V}$$

$$V^- = - \left[ \frac{120}{8} \sqrt{2} \times \frac{1}{2} \right] + 0.7$$

$$= \boxed{-9.9V}$$

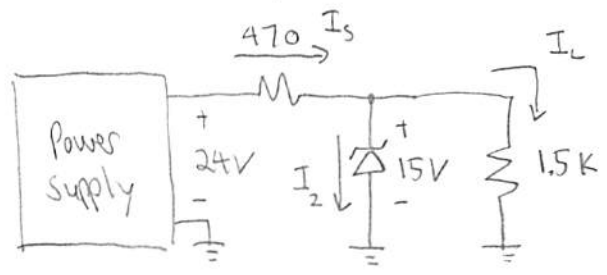


5.5 (+9)

$$I_s = \frac{24 - 15}{470} = \boxed{19.1 \text{ mA}}$$

$$I_L = \frac{15}{1.5k} = \boxed{10 \text{ mA}}$$

$$I_z = I_s - I_L = \boxed{9.1 \text{ mA}}$$



5.6 (+9) Max zener current involves lowest  $R_s$  and highest  $R_L$ .

$$I_{s,max} = \frac{24 - 15}{.95 \times 470} = \underline{\underline{20.2 \text{ mA}}}$$

$$I_{L,min} = \frac{15}{1.05 \times 1.5k} = \underline{\underline{9.5 \text{ mA}}}$$

$$I_{z,max} = I_{s,max} - I_{L,min} = \boxed{10.7 \text{ mA}}$$

5.7 (+9) Max zener current involves highest supply

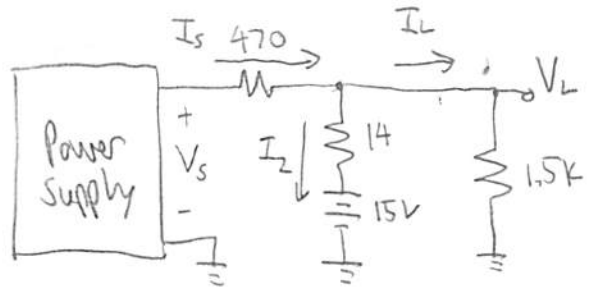
$$I_{s,max} = \frac{40 - 15}{470} = \underline{\underline{53.2 \text{ mA}}}$$

$$I_L = \frac{15}{1.5k} = \underline{\underline{10 \text{ mA}}}$$

$$I_{z,max} = I_{s,max} - I_L = \boxed{43.2 \text{ mA}}$$

5.11

49



$$I_s = I_2 + I_L$$

$$\frac{V_s - V_L}{470} = \frac{V_L - 15}{14} + \frac{V_L}{1500}$$

$$\frac{V_s}{470} + \frac{15}{14} = \left( \frac{1}{470} + \frac{1}{14} + \frac{1}{1500} \right) V_L = .074 V_L$$

$$V_L = \frac{1}{.074} \left( \frac{V_s}{470} + \frac{15}{14} \right)$$

$$V_s = 21.5V \rightarrow V_L = \boxed{15.1V}$$

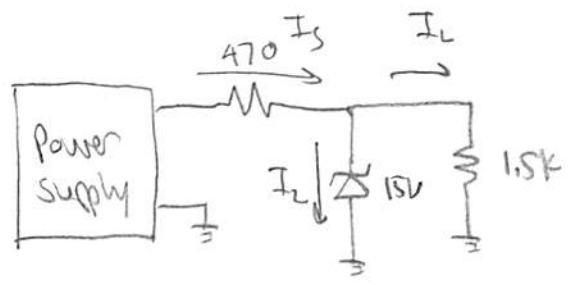
$$V_s = 25V \rightarrow V_L = \boxed{15.2V}$$

5.12

45

Drop out occurs when  $I_2 = 0$

$$\rightarrow I_s = I_L$$



$$\frac{V_s - 15}{470} = \frac{15}{1500}$$

$$V_s = \left( \frac{15}{1500} + \frac{15}{470} \right) 470 = \boxed{19.7V}$$

← Voltage regulation is completely gone.

Note: Regulation becomes poor when  $I_2 \leq 10 \text{ mA}$

5.13 (+9)

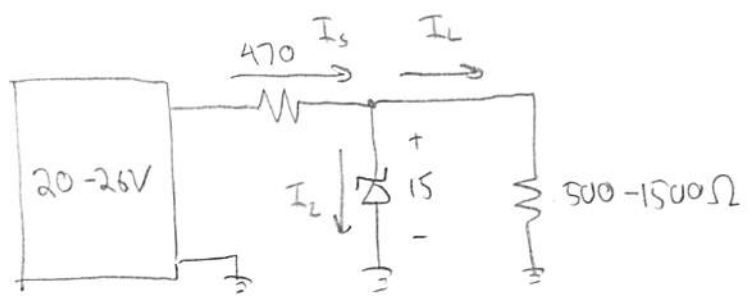
worst case scenario:

$$I_2 = I_s - I_L$$

$$= \frac{20-15}{470} - \frac{15}{500}$$

$$= 10.6 \text{ mA} - 30 \text{ mA} = -19.4 \text{ mA} < 0 \text{!}$$

YES, the zener regulator will fail. ☹



want  $I_{z,min} = 0 = \frac{20-15}{R_{s,max}} - \frac{15}{500}$

$$R_{s,max} = (20-15) \frac{500}{15} = \boxed{167\Omega}$$

NOTE: In practice,  $R_s$  should be lower than this to keep  $I_z > 10 \text{ mA}$ .

5.14

(+9)

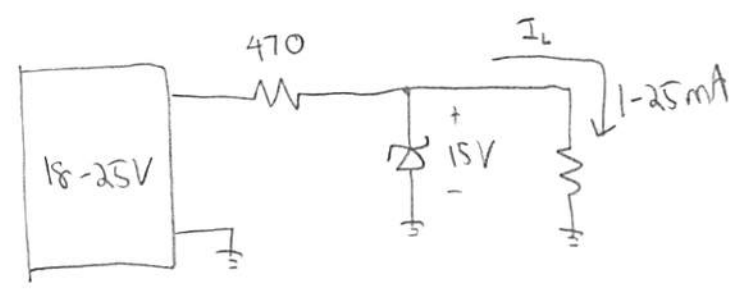
worst case scenario:

$$I_2 = I_s - I_L$$

$$= \frac{18-15}{470} - 25 \text{ mA}$$

$$= -18.6 \text{ mA} < 0 \text{!}$$

YES, the zener will fail. ☹



want  $I_{z,min} = 0 = \frac{18-15}{R_{s,max}} - 25 \text{ mA}$

$$R_{s,max} = \frac{3}{25 \text{ mA}} = 0.12 \text{ k} = \boxed{120\Omega}$$

NOTE: In practice,  $R_s$  should be lower than this to keep  $I_z > 10 \text{ mA}$